Recall several properties of graphs and the algorithms that compute them:

- **maxmimum flow:** The largest value to place on each edge, subject to edge and vertex conditions, to maximize flow from the source to the sink
 - the $\mathit{Ford-Fullkerson}$ algorithm increases flow capacity along paths step by step until the maximum flow is reached on that path
- shortest path: The path with the least weight between nodes
 - Dijkstra's algorithm does a breadth-first greedy search from a root node
 - the $Bellman-Ford\ algorithm$ recalculates distance to every edge at each step
- minimum spanning tree: The smallest weight subtree that that spans the graph
 - Kruskal's algorithm builds clusters by adding minimal weight edges
 - Prim's algorithm starts at a root node and adds minimal weight edges
- 1. Warm up: Answer the following questions.
 - (a) What does a connected graph for which BFS and DFS reaches a given node node in the same number of steps look like?
 - (b) Is it possible to have a connected graph with two spanning trees that do not share any edges?
 - (c) What condition on a binary tree will guarantee that it does not have a perfect matching?
- 2. For the graph G below, and the root node 0, add weights to the edges so that the minimal spanning trees built by Kruskal's and Prim's algorithm share the least number of edges possible. The order of the vertices indicates the order in which they are considered for each algorithm.



3. Let G = (V, E) be a graph with two different weight functions

$$w \colon E \to \mathbf{Z}, \qquad w' \colon E \to \mathbf{N} \cup \{0\},$$

with $w'(e) = w(e) - \min_{\varepsilon \in E} \{w(\varepsilon)\}$. Suppose that Bellman–Ford is run on G with weights w, and Dijkstra is run on G with weights w'. What is the relationship between the two resulting subgraphs?