Worksheet 13

10 December 2020

1. Computational complexity: The following question is about the algorithm below, which takes as input three natural numbers a, b, n.

 $\begin{array}{ll} f(a,b,n):\\ 1 & d \leftarrow 1\\ 2 & \operatorname{let} b_k b_{k-1} \cdots b_0 \text{ be the binary representation of } b\\ 3 & \mathbf{for} \ i=k,\ldots,0:\\ 4 & d \leftarrow d^2 \pmod{n}\\ 5 & \mathbf{if} \ b_i=1:\\ 6 & d \leftarrow da \pmod{n}\\ 7 & \mathbf{return} \ d \end{array}$

- (a) Give the values of d as it changes for:
 - i. f(2,3,3) ii. f(2,4,3) iii. f(2,5,3)
- (b) Suppose that every line takes constant time.
 - i. Which inputs does the running time of f depend on?
 - ii. What is the running time of f, in Big-O and Big- Ω notation?
- (c) Suppose that lines 4 and 6 take $O(n^2)$ time. In Big-O notation:
 - i. What is the running time of f, if $b = 2^k$ for some $k \in \mathbb{N}$?
 - ii. What is the running time of f, if $b = 2^k 1$ for some $k \in \mathbb{N}$?

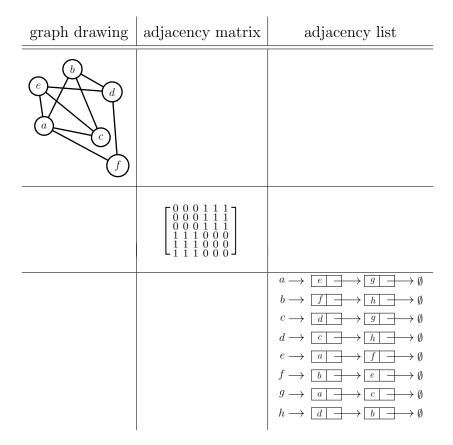
2. C++ and the STL:

- (a) What is the difference between a class and a struct?
- (b) Suppose that a class walk has been defined, containing a method talk.
 - i. Write the code, outside of the braces {...}; defining a class run derived from walk via (public) inheritance.
 - ii. Write the code, as the int main() { ... return 0;} function, that defines a class run called Gun and calls its talk method.
- (c) What is the difference between unordered_set and unordered_map in the STL?

3. Hashing and sorting:

- (a) Draw what happens when the keys 5, 28, 19, 15, 20, 33, 12, 17, 10, are insterted into a hash table with hash function $h(k) = k \pmod{9}$, with collisions resolved by chaining.
- (b) What is the running time of *quicksort* on an input array of size n, where all the array values are the same?
- (c) What is the running time of *heapsort* on an input array of size n when:
 - i. the array is already sorted? ii. the array is sorted in reverse?

- 4. Trees: Recall the nodes of a tree are either internal or external (or leaves), and they are indexed by keys. Each node has a single parent and may have one or more children. Suppose a tree has n nodes. Answer (a) and (b) in terms of Big-O and Big-Ω.
 - (a) What is the running time of inserting a new node into a *binary search tree* (BST)?
 - (b) What is the running time of inserting a new node into a *height-balanced* BST (AVL)?
 - (c) Draw the *red-black tree* resulting from inserting the keys 5, 16, 22, 45, 2, 10, 18, 30, 50, 12, 1, in this order, into an empty tree.
 - (d) Draw an example of:
 - i. a red-black tree that is not an AVL tree
 - ii. a red-black tree which after splaying a leaf is not a red-black tree anymore
- 5. Undirected graphs: Complete the table below, where each line is a graph and each column is a way to represent the graph.



- 6. Graph algorithms: Answer (a) and (b) in the context of running time, where n is the number of vertices in the input graph.
 - (a) Dijktra's and the Bellman–Ford algorithms find the *shortest path* from a vertex in a weighted directed graph. How are the two different?
 - (b) Kruskal's and Prim's algorithms find the *minimum spanning tree* in a weighted undirected graph. How are the two different?
 - (c) What type of a graph does the *topological sorting* algorithm take as input?
 - (d) What does the *travelling salesperson problem* try to find in an undirected, connected weighted graph?